

# A note on “A Note on Constraining AR(2) Parameters in Estimation”

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The following is a more detailed explanation of the result in Morley (1999):

$$b^2 = (1 - |a|) b_{uc}^2 + |a| - a^2, \quad (1)$$

where  $b_{uc}^2$  is constrained to be between -1 and 1.

As reflected in the “triangle” diagram in Hamilton (1994), for the eigenvalues of the AR(2) to remain inside the unit circle, and hence imply stationary dynamics,  $\phi_2$  must satisfy for a given  $\phi_1$ :

$$-1 \leq \phi_2 \leq 1 - \phi_1, \quad \text{if } \phi_1 \geq 0, \quad (2)$$

$$-1 \leq \phi_2 \leq 1 + \phi_1, \quad \text{if } \phi_1 < 0. \quad (3)$$

Since the triangle is symmetric about  $\phi_1 = 0$ , the bounds for  $\phi_2$  do not depend on the *sign* of  $\phi_1$ . Therefore, if we consider the absolute value of  $\phi_1$  instead, the only constraints on  $\phi_2$  are:  $-1 \leq \phi_2 \leq 1 - |\phi_1|$ .

Then, using  $\phi_1 = 2a$  and  $\phi_2 = -(a^2 + b^2)$ , it can be easily shown that

$$-1 + 2|a| - a^2 \leq b^2 \leq 1 - a^2. \quad (4)$$

Morley (1999) states that equation (1) satisfy the constraints. To see this, note that as  $b_{uc}^2 \rightarrow -1$ ,  $b^2 \rightarrow -1 + 2|a| - a^2$ , and as  $b_{uc}^2 \rightarrow 1$ ,  $b^2 \rightarrow 1 - a^2$ . In addition, note that equation (1) is linear function of  $b_{uc}^2$  for a given  $a$ .